

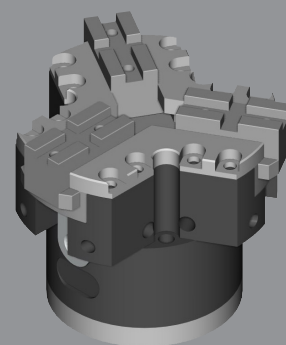
Pneumatic Parallel Grippers

MOP 3-Finger

MOP is a universal three-finger parallel gripper featuring high repeatability and long service life, suitable for a wide range of industrial applications.

Advantages

- Robust and lightweight housing made of hard coated aluminum alloy.
- Sturdy T-slot with hardened steel gibs for effective jaw guidance, precise handling and easy maintenance.
- Lever design for high-force transmission and jaw synchronization.
- Mounting from two sides in three screw directions for versatile and flexible integration.
- Air supply via hose-free direct connections or fitting screw connections.



SPECIFICATIONS

Model	Stroke Per Jaw	Air Consumption Per Cycle (Dual Stroke)	Closing Force Per Jaw @ 6 bar	Opening Force Per Jaw @ 6 bar	Total Closing Force @ 6 bar	Total Opening Force @ 6 bar	Recommended Workpiece Weight*	Weight	Repeatability
MOP 653	10 mm	31 cm ³	147.4 N	442.2 N	2.21 kg	1.1 kg	2.21 kg	0.11 kg	± 0.01 mm
	0.39 in	1.89 in ³	33.1 lb	66.3 lb	4.9 lb	2.42 lb	4.90 lb	0.24 lb	± 0.0004 in

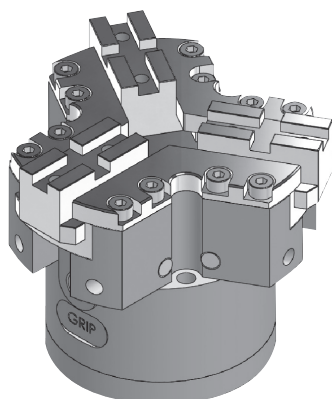
* Recommended workpiece weight is calculated for force-fit gripping with a coefficient of static friction of 0.15 and a safety factor of 3 against workpiece slippage.

Operating Pressure **2 - 12 bar (29 - 174 psi)**

Working Temperature **5 - 60 °C (41 - 140 °F)**

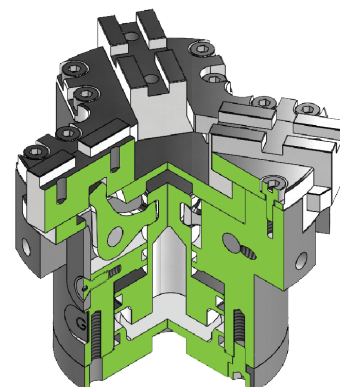
Noise Emission (Sound Pressure) **≤ 70 dB(A) in any direction**

SECTIONAL DIAGRAM



Guidelines for the selection of a gripper model

Selection of the correct gripper model depends on the workpiece's weight, the friction coefficient between the fingers and the workpiece and the required motion of the application. Due to inertial forces associated with motion, we recommend that the holding force of the gripper model should be from 10 to 20 times the workpiece's weight. If the application presents high acceleration/deceleration or impacts during the motion, then a further safety margin should be considered.

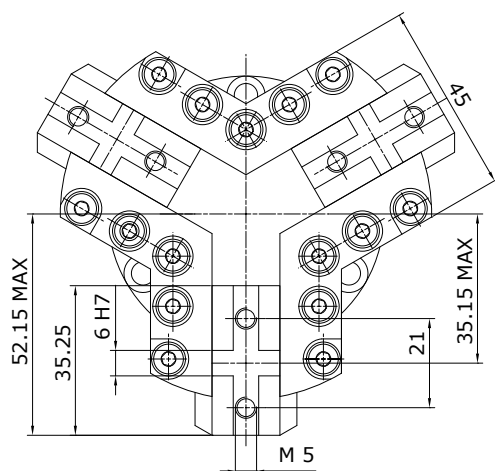
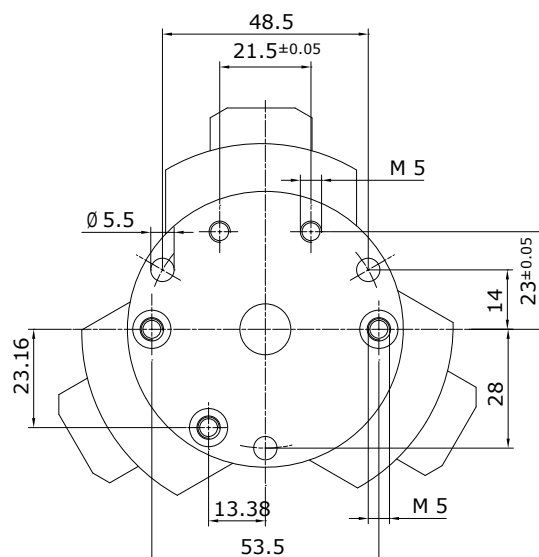
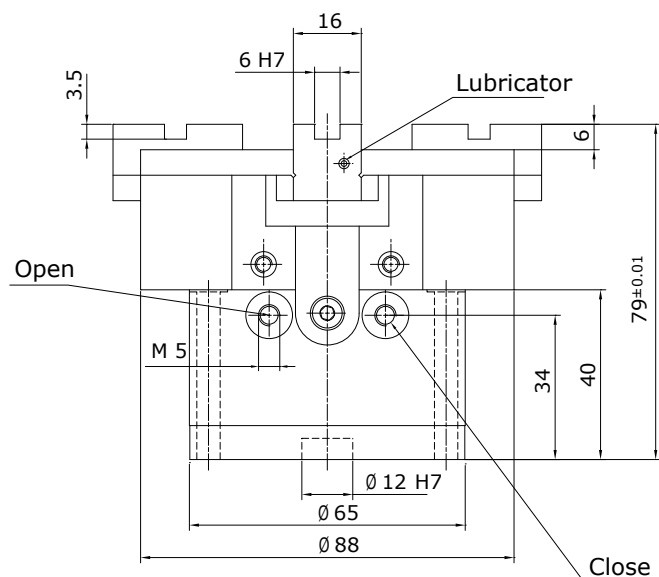


PRODUCT INFORMATION

MOP 3-Finger



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* Dimensions are in millimeters (inches).

** All dimensions are descriptive and subject to variation for technical upgrading. We reserve the right to make variations without prior notification



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